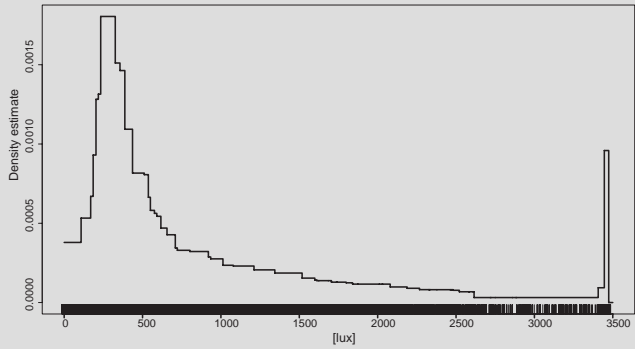


# Integrating R in an advanced building control system



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# The LESO-PB building



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# Bayes's theorem

$$\Pr(C = \text{False} | E = e) =$$

$$\frac{\Pr(E = e | C = \text{False}) \Pr(C = \text{False})}{\Pr(E = e | C = \text{False}) \Pr(C = \text{False}) + \Pr(E = e | C = \text{True}) \Pr(C = \text{True})}$$

$$\Pr(E = e | C = \text{False}) \Pr(C = \text{False}) + \Pr(E = e | C = \text{True}) \Pr(C = \text{True})$$

Illuminance distribution for uncomfortable situations

Illuminance distribution for comfortable situations

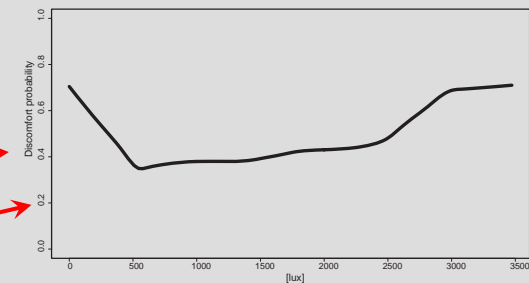
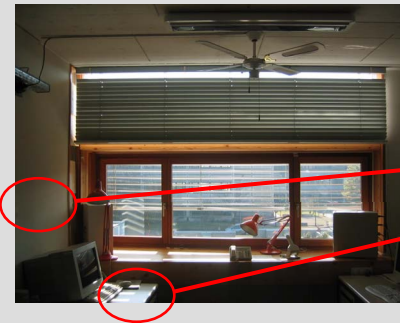
cf. email classifiers:  $\Pr(\text{Spam} = \text{True} | \text{Content} = \text{"Nigeria"})$



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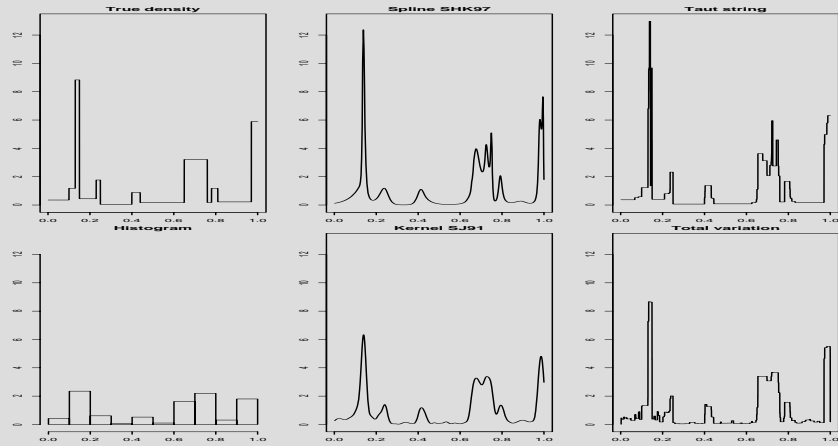
# User discomfort probability



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# Density estimation methods

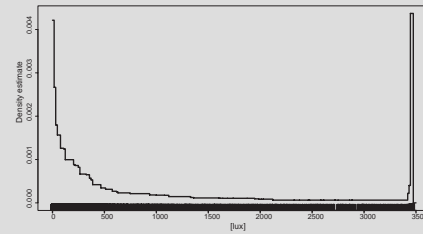


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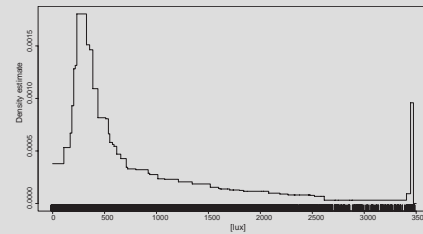


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# Density estimation with Davies & Kovac's `ftnonpar` package



$$\Pr(E = e | C = False)$$



$$\Pr(E = e | C = True)$$

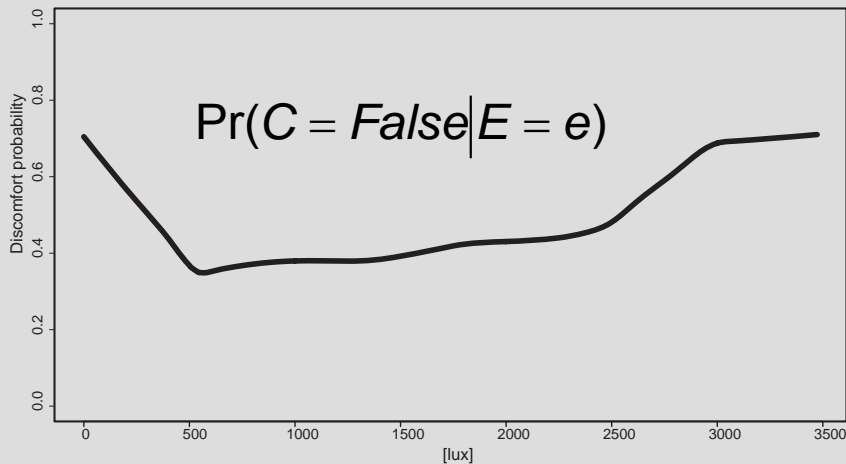


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# Discomfort probability

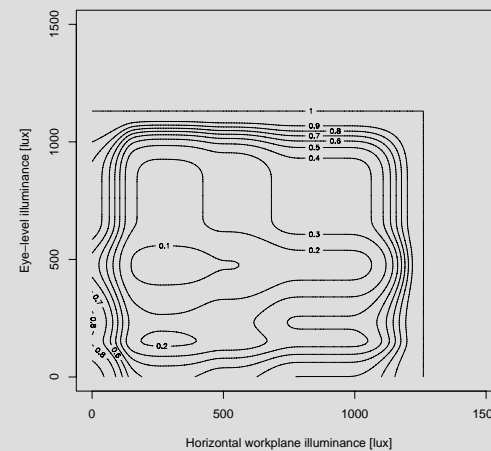


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# Combination of variables



Horizontal and eye-level  
illuminances



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# Summary

- R called from a Java program to perform density estimation with taut-string algorithm
- Data prepared with an R script, then Davies & Kovac's `ftnonpar` package computes the estimation



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